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# A survey on air pollutant PM2.5 prediction using random forest model

Sherin Babu<sup>1,2\*</sup>, Binu Thomas<sup>2,3</sup>

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<sup>1</sup>Department of Computer Science, Assumption College Autonomous, Changanacherry, Kottayam, Kerala, India <sup>2</sup>School of Computer Sciences, Mahatma Gandhi University, Kottayam, Kerala, India

<sup>3</sup>Department of Computer Applications, Marian College Autonomous, Kuttikanam, Idukki, Kerala, India

#### Abstract

**Background:** One of the most critical contributors to air pollution is particulate matter ( $PM_{2.5}$ ) that its acute or chronic exposure causes serious health effects to human. Accurate forecasting of  $PM_{2.5}$  concentration is essential for air pollution control and prevention of health complications. A survey of the available scientific literature on random forest model for  $PM_{2.5}$  prediction is presented here.

**Methods:** The scientific literature is extracted from Science Direct database based on a set of specified search criteria. The input features, data length, and evaluation parameters used in PM<sub>2.5</sub> prediction were analyzed in this study.

**Results:** The study shows that majority of the publications are aimed at the daily prediction of outdoor  $PM_{25}$ . Most publications base their  $PM_{25}$  prediction on features aerosol optical depth (AOD) and boundary layer height (BLH).  $PM_{10}$  and  $NO_2$  are the main air pollutants employed in the  $PM_{25}$  estimation. Majority studies utilized input data lengths covering more than one year, and the effectiveness of prediction models are unaffected by the length of investigation. The coefficient of determination,  $R^2$ , is the primary evaluation parameter used in all publications. The majority of research study indicated  $R^2$  values greater than 0.85, demonstrating the reasonable dependability and efficiency of random forest regression-based  $PM_{25}$  prediction models.

**Conclusion:** The study demonstrates that the publications use a variety of meteorological and geological features for PM<sub>2.5</sub> estimation, depending on the context of the research as well as data accessibility. The findings demonstrate that it is hard to pinpoint the optimal model in any particular way. **Keywords:** Air pollution, Air pollutants, Aerosols, Particulate matter, Machine learning

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# Introduction

Air pollution is considered as a serious threat to public health across the world. It can adversely affect the length and quality of human life. In 2018, the World Health Organization (WHO) reported that about 90 percent of people around the world breathe polluted air (1). Particulate matter (PM25) is a term used to describe fine, inhalable mixtures of solid and liquid particles with diameters smaller than 2.5 µm that can linger in the atmosphere for an extended period of time and pose major health risks (2,3). Fuel combustion and atmospheric chemical processes result in the formation of these particles. Fine particulate matter air pollutant (PM<sub>1</sub>) is a significant public health problem, especially for older people and young children (4,5). PM<sub>2</sub> can penetrate deeply into the lungs, and hence, the exposure to high concentrations of PM will cause respiratory and cardiovascular diseases (6-9). High concentrations of Article History: Received: 24 May 2022 Accepted: 10 December 2022 ePublished: 25 May 2023

\*Correspondence to: Sherin Babu, Email: sherinbabu@ assumptioncollege.edu.in

PM<sub>25</sub> in the lower atmosphere can lead to the formation of haze, which causes slight obscuration in the visibility, and thus, leading to road accidents and transportation delays (10). In a large number of recent time-series studies, the atmospheric particulate matter has been reported as a causal factor for morbidity (11-14). Studies have revealed that the exposure to fine particulate matter over a long term cause increased mortality rate (15-18). In 2017, the Global Burden of Diseases report ranked particulate matter out of a list of 84 risk factors as the sixth leading cause of human death (19). In light of these findings, environmental scientists and public health workers all around the world are becoming more concerned about the rising trend of particulate matter in the metropolitan areas. Air pollutant concentration predicting is an effective way of protecting public health by providing an early warning, and also, for taking precautionary actions and in turn, ensuring clean and fresh air in the future.

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Machine learning (ML) systems possess the ability to learn automatically without specific programming and develop from experience (20). Today, in almost all fields of research, the application of machine learning techniques can be found, from plant identification to drug discovery. Machine learning techniques can identify patterns and associations underlying the large and complex datasets, and thus, generate knowledge from them (21-23). Increased computing capacity allowed the development of advanced machine learning algorithms such as multiple linear regression, artificial neural networks, support vector machines (SVM) regression, random forest regression (RFR), and deep learning models for accurate and efficient prediction of various air pollutants (24,25). Studies have shown that the prediction of air pollutant concentrations by machine learning algorithms resulted in higher prediction accuracy.

Random forest is a machine-learning algorithm for classification and regression, which uses an ensemble of decision trees, with ample strength in handling complex nonlinear relationships within variable (26,27). Random forest is a method of ensemble learning that provides high precision and interpretability for predictions (28-30). Random forest allows nonlinearities and interactions to be learned from the data without any need to explicitly model them, thus, enabling them to exhibit superior performance to traditional statistical models (31-33). RFR is a supervised learning algorithm that uses an ensemble learning method for regression. In RFR, each node is divided into two or more child nodes, using the best subset of predictors randomly selected at that node. The data in each child node is used to predict dependent variable values within that node. The results are then combined from all child nodes to generate final predictions (26,34,35).

There are air pollution prediction surveys that have been released with different emphases in recent years. But no research surveys are being carried out on the estimation of PM<sub>2.5</sub> using machine learning methods. One of the finest regression algorithms for features with non-linear correlations is RFR, which offers improved accuracy, reduction of overfitting, and performs well. Therefore, this investigation was conducted to get an overview of what research work has been done regarding the application of the random forest algorithm in the PM<sub>2.5</sub> prediction. This will help recognize the potential gaps in this research area and lead the new researchers in the field to understand the state of the art.

#### Materials and Methods

This survey aimed to get insight into what studies have been published in the domain of air pollutant PM<sub>2.5</sub> prediction and random forest technique. Before conducting the survey, the research questions were defined. For this survey, the following three research questions (RQs) were defined:

- RQ1 Which are the input features or variables used in the scientific literature for PM2<sub>.5</sub> prediction using random forest technique?
- RQ2 What is the input data length used in the scientific literature for PM<sub>2.5</sub> prediction using random forest technique?
- RQ3 Which are the evaluation parameters used in the scientific literature for PM<sub>2.5</sub> prediction using random forest technique?

When research questions were ready, the database for conducting the study was selected. The database used in this study is Science Direct. The data for this study were retrieved on December 18, 2020. The search string used for extracting the relevant literature is ["PM\_25" AND "prediction" AND "random forest"]. This string is searched by the title, abstract, and keywords. After the search process, the obtained results were filtered and assessed using a set of exclusion criteria.

- Exclusion criteria 1 The publication is not a research article.
- Exclusion criteria 2 The publication year is not 2019.
- Exclusion criteria 3 The language of publication is not English.
- Exclusion criteria 4 Full text of the publication is not available.

# Results

On the basis of the search string, 27 research publications were extracted during the search process. Then, the exclusion criteria were applied, and only eight full text publications remained for further analysis. During the data analysis, all the extracted data were investigated thoroughly, and the research questions were answered accordingly. The resultant publications of the query are shown in Table 1. In this table, the title of the research articles and journal of publication of these articles are presented.

Bai et al (36) proposed a random forest-based PM<sub>2.5</sub> data mining framework for the improvement of PM<sub>2.5</sub> prediction accuracy in eastern China. In this study, Gaussian-kernelbased interpolators were built to use PM<sub>2.5</sub> information from nearby sites and near-term historical observations to estimate spatially and temporally lagged PM<sub>2.5</sub> terms. For more precise PM<sub>2.5</sub> mapping, the predicted prior PM<sub>2.5</sub> details and variables such as aerosol optical depth (AOD) and meteorological conditions were then integrated into RFR models. The study claimed that the presence of ground-based PM<sub>2.5</sub> mapping precision. For regions with no prior PM<sub>2.5</sub> knowledge or for regions with few PM<sub>2.5</sub> monitoring sites, the prediction model did not work either.

Bi et al (37) developed a PM<sub>2.5</sub> prediction model based on the random forest algorithm to estimate fully covered and high-resolution ground PM<sub>2.5</sub> in New York State in

Table 1. Resultant publications

Authors	Title of the article	Journal
Bai et al (36)	Advancing the prediction accuracy of satellite-based PM $_{2.5}$ concentration mapping: A perspective of data mining through in situ PM $_{2.5}$ measurements	Environmental Pollution
Bi et al (37)	Impacts of snow and cloud covers on satellite-derived PM_25	Remote Sensing of Environment
Di et al (38)	An ensemble-based model of ${\rm PM}_{_{2.5}}$ concentration across the contiguous United States with high spatiotemporal resolution	Environment International
Li and Zhang (39)	Predicting ground-level PM concentrations in the Beijing-Tianjin-Hebei region: A hybrid remote sensing and machine learning approach	Environmental Pollution
Nabavi et al (40)	Assessing PM concentrations in Tehran, Iran, from space using MAIAC, deep blue, and dark target AOD and machine learning algorithms	Atmospheric Pollution Research
Stafoggia et al (41)	Estimation of daily $\rm PM_{_{10}}$ and $\rm PM_{_{2.5}}$ concentrations in Italy, 2013–2015, using a spatiotemporal land-use random-forest model	Environment International
Tang et al (42)	Comparison of GOCI and Himawari-8 aerosol optical depth for deriving full-coverage hourly ${\rm PM}_{_{2.5}}$ across the Yangtze River Delta	Atmospheric Environment
Wei et al (43)	Estimating 1-km-resolution $\mathrm{PM}_{_{25}}$ concentrations across China using the space-time random forest approach	Remote Sensing of Environment

2015. The model takes into account satellite AOD and the impacts of snow and cloud covers on AOD for PM predictions. The author argued that this is the first research work that considered the snow-AOD relationship for PM, modelling. In order to estimate the missing AOD, a daily gap-filling model with snow and cloud fractions and meteorological explanatory variables were developed using the random forest algorithm. By using this gap-filled AOD model in New York State, a daily AOD data set with a 1-km resolution was generated for 2015. Then, a random forest model based on the gap-filled AOD and covariates was built to predict fully covered PM25 estimates. The study was able to ascertain the importance of cloud and snow parameters in estimating the air pollutant PM and the discernible interactions between snow/cloud and AOD/PM<sub>25</sub>. The drawback of the research is that it took into account only the coverage of snow and cloud, not the physical features of snow and cloud.

Di et al (38) developed an ensemble model that combined three machine learning algorithms called the neural network, random forest, and gradient boosting and predictor variables to estimate daily PM25 concentrations at a resolution of 1 km × 1 km across the contiguous United States from 2000 to 2015. The three-machine learning algorithms were fed with satellite data, meteorological variables, land-use variables, elevation, chemical transport model predictions, land use data, and few other reanalysis data. Thus, the predicted values of PM25 were obtained from each learner. The study also calculated spatially and temporally lagged PM25 predictions from nearby monitoring sites and neighboring days and treated them as additional input variables along with the above-mentioned PM, predictions. Then, a generalized additive model that accounted for the geographic difference to combine PM<sub>25</sub> estimates from the neural network, random forest, and gradient boosting was used as an ensemble model to combine PM<sub>25</sub> estimation. The benefit of research work is that the combined PM<sub>2.5</sub> estimates of the generalized

additive model from three-machine learning algorithms allowed each algorithm's contribution to differ by location.

Li and Zhang (39) proposed a hybrid remote sensing and machine learning model, termed as remote sensingrandom forest, which incorporated AOD, weather variables and air pollution variables into a modelling framework to predict daily PM225 values in Beijing-Tianjin-Hebei (BTH) region of China. The study aimed to predict the spatiotemporal distributions of daily PM\_ concentrations across the BTH region during 2015-2017. The study took into account the dynamic and large monitoring capacity of AOD and the benefits of the RF technique in the management of complex nonlinear relationships. In addition, meteorological and air contaminant variables to predict daily PM25 concentrations were incorporated into a general structure. The authors claimed that the model provides decision support for air pollution control at a regional environment during haze periods.

Nabavi et al (40) suggested a model for the spatial estimation of PM<sub>2</sub>, using 10-km merged dark target and deep blue (DB\_DT)-dependent AOD and 1-km Multi-Angle Implementation of Atmospheric Correction (MAIAC) AOD over Tehran, Iran. The authors argued that the limitations of the ground-based PM<sub>2.5</sub> measurements constrained them to estimate PM<sub>2.5</sub> using satellite AODfed statistical models. The researchers used both the MAIAC AOD algorithm, which provided a good estimate of the recovery of aerosols over both dark and light surfaces, and the DB-AOD algorithm, which provided efficient aerosol recovery over bright surfaces. Afterwards, planetary boundary layer height (PBLH) and relative humidity were used for the normalization of AOD and correction of PM, respectively. Then, the performance of four machine-learning algorithms namely RF, gradient boosting, multivariate adaptive regression splines, and SVM were investigated in the spatial estimation of PM. The study established that RF model fed by normalized 10-km DB\_DT AOD yielded the most accurate estimate

of PM<sub>2.5</sub> over Tehran region. The authors concluded that the use of high-resolution MAIAC AOD could not improve the prediction ability of any of the machine-learning algorithms employed here compared to 10-km DB\_DT AOD.

Stafoggia et al (41) developed a five-stage random forest model to predict daily PM10, PM25, and PM25-10 concentrations at fine spatial resolution in Italy during 2013 to 2015. In stage 1,  $\mathrm{PM}_{_{2.5}}$  and  $\mathrm{PM}_{_{2.5-10}}$  concentrations were predicted where only PM<sub>10</sub> data were available. Stage 2 dealt with the assignment of missing satellite AOD data using atmospheric ensemble model. In stage 3, a relationship between measured PM concentrations and satellite, land use and meteorological parameters was established. Stage 4 involved applying the stage 3 model to each 1-km<sup>2</sup> grid cell in Italy. Stage 5 aimed to improve predictions done at stage 3, by using additional information at a finer spatial resolution. The authors argued that they were successful in predicting the daily  $PM_{10}$ ,  $PM_{2.5}$ , and  $PM_{2.5-10}$  concentrations in Italy using this five-stage random forest model with high accuracy rate. The model's downside was the low performance for PM<sub>2.5-10</sub> estimation, in Southern Italy and during the summer months.

Tang et al (42) performed a comparative evaluation of the performance of the Geostationary Ocean Color Imager (GOCI) AOD and Himawari-8 AOD datasets in predicting the hourly PM<sub>2.5</sub> in Yangtze River Delta (YRD) region of China at a spatial resolution of 1 km for 2017. The comparative evaluation was done using the nonparametric approach with two random-forest submodels. The full-coverage AOD dataset was generated with the first RF sub-model, followed by the second RF sub-model for the PM<sub>2.5</sub> estimation. The first RF-submodel analysis showed that in 2017, AOD obtained from the GOCI and the Hiamwari-8 showed moderately similar trends across YRD. Similar performance was also shown by the second RF sub-model estimate of hourly PM<sub>2.5</sub> concentrations using the GOCI and Himawari-8.

Wei et al (43) estimated  $PM_{2.5}$  concentrations based on the MAIAC-AOD product using a space-time random forest (STRF) model, across China for 2016. In order to produce 1-km daily  $PM_{2.5}$  concentrations, the STRF model considered MAIAC-AOD data, along with meteorological conditions, land use and human activities. It was revealed that the STRF model was superior to those of commonly used regression models, in both model efficiency and predictive capacity.

## Discussion

Based on the three research questions, a review of the current collection of scientific literature on the random forest model for  $PM_{2.5}$  prediction was conducted. To address the research questions RQ1, RQ2, and RQ3, the input features used, the year of study, and the evaluation

parameters employed in the publications were investigated and summarized. The RQ parameters and data extracted along with the article title are shown in Table 2.

All the 8 selected publications, except Stafoggia et al (41) considered  $PM_{25}$  as a single dependent variable. Stafoggia et al (41) model estimated the particulate matter PM<sub>10</sub> and PM<sub>25</sub>. The features extracted are grouped to provide a clear description of the independent variables (features). The independent variables are grouped into meteorological, air pollutants, satellite-derived AOD, transportation and traffic, population, land use, normalized difference vegetation index (NDVI), and road data. All the publications employed more than one independent feature group for the estimation of PM25. The survey found that the key feature used by all the selected publications was AOD. AOD is a measurement that tells us how much direct sunlight is prevented by particles such as smoke, dust and haze from reaching the ground. The next widely used feature group is meteorological features. The variables that define atmospheric chemistry are known as meteorological parameters. The most common meteorological variables utilized are temperature, wind speed, surface pressure, and relative humidity. PM<sub>10</sub>, BLH, and NO<sub>2</sub> are the next prominent input features used by the majority of the publications. Only a few research works used air pollutants such as ozone, SO<sub>2</sub>, CO, etc. for the estimation of PM<sub>2.5.</sub> The only research work that employed the input features of snow cover is the research by Bi et al (37).

The research input data length used in the selected papers was divided into three groups: the study period less than or equivalent to 1 year, the study period longer than one year and less than five years, and the study period longer than five years. Out of the eight selected publications, four papers utilized input data with a length spanning more than one year, but less than five years. Furthermore, the use of data covering a period of less than one year occurred in 2 papers, while only two studies utilized data with lengths of more than five years.

All the resultant publications were aimed to predict outdoor PM25, and none of the papers concentrated on the estimation of indoor PM25. Out of the 8 publications, 5 publications estimated daily PM<sub>25</sub> values and 3 publications estimated hourly PM25 values. The studies by Li et al (39), Nabavi et al (40), and Tang et al (42) estimated hourly PM225 values. All other five papers concentrated on the daily estimation of PM<sub>2.5</sub> values. Most of the selected publications measured the concentration of PM<sub>25</sub> in China, followed by the United States of America, Iran, and Italy. All the selected publications analyzed the model performance using the evaluation parameter R<sup>2</sup>. R<sup>2</sup>, known as goodness-of-fit, specifies the percentage of the variance in the dependent variable that is predictable from the independent variables. The study by Li and Zhang (39) reported the highest  $R^2$  value ( $R^2 = 0.93$ ), followed by the

Table 2. Research question parameters used in the publications

Reference	Features used	Year of study	Evaluation parameter
Bai et al (36)	24-h averaged PM $_{_25}$ , AOD, temperature at 2 m (T), wind speed components at 10 m (U and V, m/s), PBLH (m), and RH (%), NDVI, and tropospheric NO $_2$ column density	2015-2016	Coefficient of determination (R <sup>2</sup> ), MPE, RPE
Bi et al (37)	Daily PM <sub>2.5</sub> , AOD, coverage of snow and cloud, air temperature, dew-point temperature, surface pressure, specific humidity, wind speed, visibility, PBLH, potential evaporation, downward shortwave radiation, and convective available potential energy known as CAPE, land-use parameters, population, distances to highways and major roads, elevation, NDVI and dummy variables for months and Julian days	2015	R <sup>2</sup> , RMSE
Di et al (38)	24-h averaged PM <sub>2.5</sub> , AOD, accumulated total precipitation, air temperature, downward shortwave radiation flux, accumulated total evaporation, PBLH, low cloud area fraction, perceptible water for the entire atmosphere, pressure, specific humidity at 2 m, visibility, wind speed, medium cloud area fraction, high cloud area fraction, and albedo, chemical transport model-based data, Land-use coverage types from the National Land Cover Database including barren land, forest, shrubland, herbaceous land, cultivated land, developed areas, and wetlands. Other factors – elevation, road density, restaurant density, elevation, and NDVI	2000-2015	R², RMSE
Li and Zhang (39)	Hourly ground-level $PM_{2.5}$ , AOD, meteorological variables (air temperature, relative humidity, wind speed, wind direction and pressure), and air pollutant variables (SO <sub>2</sub> , NO <sub>2</sub> , CO, O <sub>3</sub> )	2015-2017	R <sup>2</sup> , RMSE
Nabavi et al (40)	Hourly PM $_{25}$ , combined DB_DT AOD, combined MAIAC AOD, solar zenith angle, relative humidity, PBLH, road density, wind speed, visibility, minimum temperature, mean temperature, maximum temperature, elevation, and day of the year	2011-2016	R <sup>2</sup> , RMSE, MRE
Stafoggia et al. (41)	Daily PM <sub>2.5</sub> , air temperature, PBL (hh 00.00), Julian day, Barometric pressure, elevation, PBL (hh 12.00), wind (v component), AOD (470 nm), AOD (550 nm), month, latitude, administrative region, precipitations, longitude, wind (u component), distance from sea, resident population, distance from emission points, distance from highways, geoclimatic zone, density of local streets, PM <sub>10</sub> emissions from point sources, % low development, NDVI, PM <sub>10</sub> emissions from areal sources, day of week, distance from airport, % arable land, distance from major roads, light at night, % deciduous, % agricultural, density of major and minor roads, % shrub, % crops, desert dust advection, % high development, % evergreen, imperviousness surface areas,% pasture, and density of highways	2013-2015	R <sup>2</sup> , RMSPE
Tang et al (42)	Hourly PM_5, hourly AOD data from the GOCI and Himawari-8 products, AERONET AOD data, elevation, NDVI, hourly PBLH, land use types, atmospheric pressure, relative humidity, precipitation, temperature, vapor pressure, and wind field, population density data, and road density	2017	R <sup>2</sup> , RMSE, RPE
Wei et al (43)	Daily PM <sub>2.5</sub> , daily MAIAC AOD, AERONET AOD, 2-m air temperature, total precipitation, evaporation, BLH, 10-m U/V wind components, relative humidity, surface pressure, wind speed and wind direction, land-related variables, and population-related variables	2015-2016	R <sup>2</sup> , RMSE, MPE

Abbreviations: NDVI, normalized difference vegetation index; AOD, aerosol optical depth; PBLH, planetary boundary layer height; RH, relative humidity; MPE, mean prediction error; RPE, relative prediction error; MRE, mean relative error; MAIAC, Multi-Angle Implementation of Atmospheric Correction; RMSPE, root mean squared prediction error; RMSE, root mean square error.

study of Di et al (38) with  $R^2 = 0.89$ . The studies by Bai et al (36) and Tang et al (42) reported the prediction accuracy of  $R^2 = 0.86$ . The next major evaluation parameter used is RMSE. RMSE is a method by which the difference between a model's predicted values and their actual values can be measured. Of the 8 publications, 6 publications employed RMSE as an evaluation parameter and the lowest RMSE reported is 1.78 µg/m<sup>3</sup> for the studies by Bi et al (37).

#### Conclusion

 $PM_{2.5}$  is an air pollutant that has a wide variety of adverse health effects on the general wellbeing. For air pollution control, mapping  $PM_{2.5}$  concentration is thus of vital importance. A survey of random forest-based prediction models for  $PM_{2.5}$  prediction was performed in this study. The study showed that depending on the scope and background of the research and the availability of data, the selected publications use a variety of input features, both meteorological and geological features for the estimation of  $PM_{2.5}$ . AOD is the most important input feature that is utilized in most research studies. The predominant air pollutant features used in the studies are  $PM_{10}$  and NO<sub>2</sub>. It

was discovered that BLH is a major meteorological input element in the RFR-based PM25 prediction. In the majority of research studies, input data lengths that span more than a year were used. It is noteworthy that the length of the study has no effect on the accuracy and performance of the prediction models. The RFR-based PM<sub>2.5</sub> estimating models performed well, despite the investigation lasting between one and two years. The performance measuring metric that is most frequently employed across all publications is the coefficient of determination (R<sup>2</sup>). The majority of studies reported R<sup>2</sup> values more than 0.85, showing that the RFR-based PM25 prediction models are relatively reliable and effective. RMSE is another performance measuring metric that is frequently used in research publications. The results showed that no specific conclusion could be drawn as to what the best model is. This study provided a concise and comprehensive reference for researchers in the field of a random forestbased machine learning model for PM<sub>25</sub> prediction.

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# Authors' contribution

Conceptualization: Sherin Babu. Data curation: Sherin Babu. Formal analysis: Sherin Babu, Binu Thomas. Funding acquisition: Sherin Babu. Investigation: Sherin Babu, Binu Thomas. Methodology: Sherin Babu. Project administration: Binu Thomas. Resources: Binu Thomas. Software: Sherin Babu. Supervision: Binu Thomas. Validation: Binu Thomas. Visualization: Sherin Babu. Writing-original draft: Sherin Babu. Writing-review & editing: Sherin Babu, Binu Thomas.

# **Competing interests**

The authors declare that there is no conflict of interests.

# **Ethical issues**

The authors confirm that all data acquired during the research are as stated in the paper, and no data from the study has been or will be published elsewhere.

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