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A survey on air pollutant PM2.5 prediction using random forest model

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Abstract

Background: One of the most critical contributors to air pollution is particulate matter (PM_{2s}) that its acute or chronic exposure causes serious health effects to human. Accurate forecasting of PM_{25} concentration is essential for air pollution control and prevention of health complications. A survey of the available scientific literature on random forest model for $PM_{2.5}$ prediction is presented here.

Methods: The scientific literature is extracted from Science Direct database based on a set of specified search criteria. The input features, data length, and evaluation parameters used in $PM_{2.5}$ prediction were analyzed in this study.

Results: The study shows that majority of the publications are aimed at the daily prediction of outdoor PM_{25} . Most publications base their PM_{25} prediction on features aerosol optical depth (AOD) and boundary layer height (BLH). PM₁₀ and NO₂ are the main air pollutants employed in the PM_{2.5} estimation. Majority studies utilized input data lengths covering more than one year, and the effectiveness of prediction models are unaffected by the length of investigation. The coefficient of determination, \mathbb{R}^2 , is the primary evaluation parameter used in all publications. The majority of research study indicated $R²$ values greater than 0.85, demonstrating the reasonable dependability and efficiency of random forest regression-based PM_{2.5} prediction models.

Conclusion: The study demonstrates that the publications use a variety of meteorological and geological features for $PM_{2.5}$ estimation, depending on the context of the research as well as data accessibility. The findings demonstrate that it is hard to pinpoint the optimal model in any particular way. **Keywords:** Air pollution, Air pollutants, Aerosols, Particulate matter, Machine learning

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Introduction

Air pollution is considered as a serious threat to public health across the world. It can adversely affect the length and quality of human life. In 2018, the World Health Organization (WHO) reported that about 90 percent of people around the world breathe polluted air (1). Particulate matter (PM_{2}) is a term used to describe fine, inhalable mixtures of solid and liquid particles with diameters smaller than 2.5 μm that can linger in the atmosphere for an extended period of time and pose major health risks (2,3). Fuel combustion and atmospheric chemical processes result in the formation of these particles. Fine particulate matter air pollutant $(PM₂)$ is a significant public health problem, especially for older people and young children $(4,5)$. PM₂ can penetrate deeply into the lungs, and hence, the exposure to high concentrations of $PM_{2.5}$ will cause respiratory and cardiovascular diseases (6-9). High concentrations of

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 PM_{25} in the lower atmosphere can lead to the formation of haze, which causes slight obscuration in the visibility, and thus, leading to road accidents and transportation delays (10). In a large number of recent time-series studies, the atmospheric particulate matter has been reported as a causal factor for morbidity (11-14). Studies have revealed that the exposure to fine particulate matter over a long term cause increased mortality rate (15-18). In 2017, the Global Burden of Diseases report ranked particulate matter out of a list of 84 risk factors as the sixth leading cause of human death (19). In light of these findings, environmental scientists and public health workers all around the world are becoming more concerned about the rising trend of particulate matter in the metropolitan areas. Air pollutant concentration predicting is an effective way of protecting public health by providing an early warning, and also, for taking precautionary actions and in turn, ensuring clean and fresh air in the future.

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Machine learning (ML) systems possess the ability to learn automatically without specific programming and develop from experience (20). Today, in almost all fields of research, the application of machine learning techniques can be found, from plant identification to drug discovery. Machine learning techniques can identify patterns and associations underlying the large and complex datasets, and thus, generate knowledge from them (21-23). Increased computing capacity allowed the development of advanced machine learning algorithms such as multiple linear regression, artificial neural networks, support vector machines (SVM) regression, random forest regression (RFR), and deep learning models for accurate and efficient prediction of various air pollutants (24,25). Studies have shown that the prediction of air pollutant concentrations by machine learning algorithms resulted in higher prediction accuracy.

Random forest is a machine-learning algorithm for classification and regression, which uses an ensemble of decision trees, with ample strength in handling complex nonlinear relationships within variable (26,27). Random forest is a method of ensemble learning that provides high precision and interpretability for predictions (28-30). Random forest allows nonlinearities and interactions to be learned from the data without any need to explicitly model them, thus, enabling them to exhibit superior performance to traditional statistical models (31-33). RFR is a supervised learning algorithm that uses an ensemble learning method for regression. In RFR, each node is divided into two or more child nodes, using the best subset of predictors randomly selected at that node. The data in each child node is used to predict dependent variable values within that node. The results are then combined from all child nodes to generate final predictions (26,34,35).

There are air pollution prediction surveys that have been released with different emphases in recent years. But no research surveys are being carried out on the estimation of PM_{2.5} using machine learning methods. One of the finest regression algorithms for features with non-linear correlations is RFR, which offers improved accuracy, reduction of overfitting, and performs well. Therefore, this investigation was conducted to get an overview of what research work has been done regarding the application of the random forest algorithm in the PM₂ prediction. This will help recognize the potential gaps in this research area and lead the new researchers in the field to understand the state of the art.

Materials and Methods

This survey aimed to get insight into what studies have been published in the domain of air pollutant PM prediction and random forest technique. Before conducting the survey, the research questions were defined. For this survey, the following three research questions (RQs) were defined:

- RQ1 Which are the input features or variables used in the scientific literature for $PM2$ ₋ prediction using random forest technique?
- RQ2 What is the input data length used in the scientific literature for PM _{2.5} prediction using random forest technique?
- RQ3 Which are the evaluation parameters used in the scientific literature for PM_{25} prediction using random forest technique?

When research questions were ready, the database for conducting the study was selected. The database used in this study is Science Direct. The data for this study were retrieved on December 18, 2020. The search string used for extracting the relevant literature is ["PM₂ AND "prediction" AND "random forest"]. This string is searched by the title, abstract, and keywords. After the search process, the obtained results were filtered and assessed using a set of exclusion criteria.

- • Exclusion criteria 1 The publication is not a research article.
- Exclusion criteria 2 The publication year is not 2019.
- Exclusion criteria 3 The language of publication is not English.
- Exclusion criteria 4 Full text of the publication is not available.

Results

On the basis of the search string, 27 research publications were extracted during the search process. Then, the exclusion criteria were applied, and only eight full text publications remained for further analysis. During the data analysis, all the extracted data were investigated thoroughly, and the research questions were answered accordingly. The resultant publications of the query are shown in [Table 1](#page-2-0). In this table, the title of the research articles and journal of publication of these articles are presented.

Bai et al (36) proposed a random forest-based PM_{2.5} data mining framework for the improvement of PM₂. prediction accuracy in eastern China. In this study, Gaussian-kernelbased interpolators were built to use PM_{25} information from nearby sites and near-term historical observations to estimate spatially and temporally lagged PM₂ terms. For more precise PM_{2.5} mapping, the predicted prior PM₂. details and variables such as aerosol optical depth (AOD) and meteorological conditions were then integrated into RFR models. The study claimed that the presence of ground-based PM_{25} neighborhood information could greatly enhance $PM_{2.5}^{\gamma}$ mapping precision. For regions with no prior PM_{2.5} knowledge or for regions with few PM_{2.5} monitoring sites, the prediction model did not work either.

Bi et al (37) developed a PM_{2.5} prediction model based on the random forest algorithm to estimate fully covered and high-resolution ground $PM_{2.5}$ in New York State in

Table 1. Resultant publications

Authors	Title of the article	Journal
Bai et al (36)	Advancing the prediction accuracy of satellite-based PM $_{2.5}^{\circ}$ concentration mapping: A perspective of data mining through in situ PM measurements	Environmental Pollution
Bi et al (37)	Impacts of snow and cloud covers on satellite-derived PM levels	Remote Sensing of Environment
Di et al (38)	An ensemble-based model of PM ₂₅ concentration across the contiguous United States with high spatiotemporal resolution	Environment International
Li and Zhang (39)	Predicting ground-level PM ₂₅ concentrations in the Beijing-Tianjin-Hebei region: A hybrid remote sensing and machine learning approach	Environmental Pollution
Nabavi et al (40)	Assessing PM _{2c} concentrations in Tehran, Iran, from space using MAIAC, deep blue, and dark target AOD and machine learning algorithms	Atmospheric Pollution Research
Stafoggia et al (41)	Estimation of daily PM ₁₀ and PM ₂₅ concentrations in Italy, 2013–2015, using a spatiotemporal land- use random-forest model	Environment International
Tang et al (42)	Comparison of GOCI and Himawari-8 aerosol optical depth for deriving full-coverage hourly PM across the Yangtze River Delta	Atmospheric Environment
Wei et al (43)	Estimating 1-km-resolution PM ₂₅ concentrations across China using the space-time random forest approach	Remote Sensing of Environment

2015. The model takes into account satellite AOD and the impacts of snow and cloud covers on AOD for PM predictions. The author argued that this is the first research work that considered the snow-AOD relationship for PM₂ modelling. In order to estimate the missing AOD, a daily gap-filling model with snow and cloud fractions and meteorological explanatory variables were developed using the random forest algorithm. By using this gap-filled AOD model in New York State, a daily AOD data set with a 1-km resolution was generated for 2015. Then, a random forest model based on the gap-filled AOD and covariates was built to predict fully covered $PM_{2.5}$ estimates. The study was able to ascertain the importance of cloud and snow parameters in estimating the air pollutant PM and the discernible interactions between snow/cloud and AOD/PM_{2.5}. The drawback of the research is that it took into account only the coverage of snow and cloud, not the physical features of snow and cloud.

Di et al (38) developed an ensemble model that combined three machine learning algorithms called the neural network, random forest, and gradient boosting and predictor variables to estimate daily PM_{25} concentrations at a resolution of $1 \text{ km} \times 1 \text{ km}$ across the contiguous United States from 2000 to 2015. The three-machine learning algorithms were fed with satellite data, meteorological variables, land-use variables, elevation, chemical transport model predictions, land use data, and few other reanalysis data. Thus, the predicted values of PM_{25} were obtained from each learner. The study also calculated spatially and temporally lagged $PM_{2.5}$ predictions from nearby monitoring sites and neighboring days and treated them as additional input variables along with the above-mentioned PM predictions. Then, a generalized additive model that accounted for the geographic difference to combine PM_{25} estimates from the neural network, random forest, and gradient boosting was used as an ensemble model to combine PM_{25} estimation. The benefit of research work is that the combined $PM_{2.5}$ estimates of the generalized

additive model from three-machine learning algorithms allowed each algorithm's contribution to differ by location.

Li and Zhang (39) proposed a hybrid remote sensing and machine learning model, termed as remote sensingrandom forest, which incorporated AOD, weather variables and air pollution variables into a modelling framework to predict daily $PM_{2,5}$ values in Beijing-Tianjin-Hebei (BTH) region of China. The study aimed to predict the spatiotemporal distributions of daily PM₂ concentrations across the BTH region during $2015 - 2017$. The study took into account the dynamic and large monitoring capacity of AOD and the benefits of the RF technique in the management of complex nonlinear relationships. In addition, meteorological and air contaminant variables to predict daily $PM_{2.5}$ concentrations were incorporated into a general structure. The authors claimed that the model provides decision support for air pollution control at a regional environment during haze periods.

Nabavi et al (40) suggested a model for the spatial estimation of PM_{25} using 10-km merged dark target and deep blue (DB_DT)-dependent AOD and 1-km Multi-Angle Implementation of Atmospheric Correction (MAIAC) AOD over Tehran, Iran. The authors argued that the limitations of the ground-based $PM_{2.5}$ measurements constrained them to estimate $PM_{2.5}$ using satellite AODfed statistical models. The researchers used both the MAIAC AOD algorithm, which provided a good estimate of the recovery of aerosols over both dark and light surfaces, and the DB-AOD algorithm, which provided efficient aerosol recovery over bright surfaces. Afterwards, planetary boundary layer height (PBLH) and relative humidity were used for the normalization of AOD and correction of $PM_{2.5}$ respectively. Then, the performance of four machine-learning algorithms namely RF, gradient boosting, multivariate adaptive regression splines, and SVM were investigated in the spatial estimation of PM_{2.5}. The study established that RF model fed by normalized 10-km DB_DT AOD yielded the most accurate estimate

of PM_{2.5} over Tehran region. The authors concluded that the use of high-resolution MAIAC AOD could not improve the prediction ability of any of the machinelearning algorithms employed here compared to 10-km DB_DT AOD.

Stafoggia et al (41) developed a five-stage random forest model to predict daily PM_{10} , $PM_{2.5}$, and $PM_{2.5-10}$ concentrations at fine spatial resolution in Italy during 2013 to 2015. In stage 1, $PM_{2.5}$ and $PM_{2.5-10}$ concentrations were predicted where only PM_{10} data were available. Stage 2 dealt with the assignment of missing satellite AOD data using atmospheric ensemble model. In stage 3, a relationship between measured PM concentrations and satellite, land use and meteorological parameters was established. Stage 4 involved applying the stage 3 model to each 1-km2 grid cell in Italy. Stage 5 aimed to improve predictions done at stage 3, by using additional information at a finer spatial resolution. The authors argued that they were successful in predicting the daily PM_{10} , $PM_{2.5}$, and $PM_{2.5-10}$ concentrations in Italy using this five-stage random forest model with high accuracy rate. The model's downside was the low performance for $PM_{2,5-10}$ estimation, in Southern Italy and during the summer months.

Tang et al (42) performed a comparative evaluation of the performance of the Geostationary Ocean Color Imager (GOCI) AOD and Himawari-8 AOD datasets in predicting the hourly PM ₂₅ in Yangtze River Delta (YRD) region of China at a spatial resolution of 1 km for 2017. The comparative evaluation was done using the nonparametric approach with two random-forest submodels. The full-coverage AOD dataset was generated with the first RF sub-model, followed by the second RF sub-model for the PM₂ estimation. The first RF-submodel analysis showed that in 2017, AOD obtained from the GOCI and the Hiamwari-8 showed moderately similar trends across YRD. Similar performance was also shown by the second RF sub-model estimate of hourly PM _{2.5} concentrations using the GOCI and Himawari-8.

Wei et al (43) estimated PM_{25} concentrations based on the MAIAC-AOD product using a space-time random forest (STRF) model, across China for 2016. In order to produce 1-km daily PM_{25} concentrations, the STRF model considered MAIAC-AOD data, along with meteorological conditions, land use and human activities. It was revealed that the STRF model was superior to those of commonly used regression models, in both model efficiency and predictive capacity.

Discussion

Based on the three research questions, a review of the current collection of scientific literature on the random forest model for $PM_{2,5}$ prediction was conducted. To address the research questions RQ1, RQ2, and RQ3, the input features used, the year of study, and the evaluation

parameters employed in the publications were investigated and summarized. The RQ parameters and data extracted along with the article title are shown in [Table 2.](#page-4-0)

All the 8 selected publications, except Stafoggia et al (41) considered $PM_{2.5}$ as a single dependent variable. Stafoggia et al (41) model estimated the particulate matter PM_{10} and PM_{25} . The features extracted are grouped to provide a clear description of the independent variables (features). The independent variables are grouped into meteorological, air pollutants, satellite-derived AOD, transportation and traffic, population, land use, normalized difference vegetation index (NDVI), and road data. All the publications employed more than one independent feature group for the estimation of PM_{25} . The survey found that the key feature used by all the selected publications was AOD. AOD is a measurement that tells us how much direct sunlight is prevented by particles such as smoke, dust and haze from reaching the ground. The next widely used feature group is meteorological features. The variables that define atmospheric chemistry are known as meteorological parameters. The most common meteorological variables utilized are temperature, wind speed, surface pressure, and relative humidity. PM_{10} , BLH, and NO₂ are the next prominent input features used by the majority of the publications. Only a few research works used air pollutants such as ozone, SO_2 , CO, etc. for the estimation of $PM_{2.5}$. The only research work that employed the input features of snow cover is the research by Bi et al (37).

The research input data length used in the selected papers was divided into three groups: the study period less than or equivalent to 1 year, the study period longer than one year and less than five years, and the study period longer than five years. Out of the eight selected publications, four papers utilized input data with a length spanning more than one year, but less than five years. Furthermore, the use of data covering a period of less than one year occurred in 2 papers, while only two studies utilized data with lengths of more than five years.

All the resultant publications were aimed to predict outdoor $PM_{2,5}$, and none of the papers concentrated on the estimation of indoor $PM_{2.5}$. Out of the 8 publications, 5 publications estimated daily PM_{25} values and 3 publications estimated hourly PM_{25} values. The studies by Li et al (39), Nabavi et al (40), and Tang et al (42) estimated hourly $PM_{2.5}$ values. All other five papers concentrated on the daily estimation of PM_{25} values. Most of the selected publications measured the concentration of PM_{2.5} in China, followed by the United States of America, Iran, and Italy. All the selected publications analyzed the model performance using the evaluation parameter \mathbb{R}^2 . \mathbb{R}^2 , known as goodness-of-fit, specifies the percentage of the variance in the dependent variable that is predictable from the independent variables. The study by Li and Zhang (39) reported the highest R^2 value ($R^2 = 0.93$), followed by the

Table 2. Research question parameters used in the publications

Abbreviations: NDVI, normalized difference vegetation index; AOD, aerosol optical depth; PBLH, planetary boundary layer height; RH, relative humidity; MPE, mean prediction error; RPE, relative prediction error; MRE, mean relative error; MAIAC, Multi-Angle Implementation of Atmospheric Correction; RMSPE, root mean squared prediction error; RMSE, root mean square error.

study of Di et al (38) with $R^2 = 0.89$. The studies by Bai et al (36) and Tang et al (42) reported the prediction accuracy of R^2 =0.86. The next major evaluation parameter used is RMSE. RMSE is a method by which the difference between a model's predicted values and their actual values can be measured. Of the 8 publications, 6 publications employed RMSE as an evaluation parameter and the lowest RMSE reported is $1.78 \,\mathrm{\upmu g/m^3}$ for the studies by Bi et al (37).

Conclusion

 PM_{25} is an air pollutant that has a wide variety of adverse health effects on the general wellbeing. For air pollution control, mapping PM_{25} concentration is thus of vital importance. A survey of random forest-based prediction models for $PM_{2.5}$ prediction was performed in this study. The study showed that depending on the scope and background of the research and the availability of data, the selected publications use a variety of input features, both meteorological and geological features for the estimation of PM_{25} . AOD is the most important input feature that is utilized in most research studies. The predominant air pollutant features used in the studies are PM $_{10}$ and NO $_{2}$. It was discovered that BLH is a major meteorological input element in the RFR-based PM₂₅ prediction. In the majority of research studies, input data lengths that span more than a year were used. It is noteworthy that the length of the study has no effect on the accuracy and performance of the prediction models. The RFR-based $PM_{2.5}$ estimating models performed well, despite the investigation lasting between one and two years. The performance measuring metric that is most frequently employed across all publications is the coefficient of determination (R^2) . The majority of studies reported \mathbb{R}^2 values more than 0.85, showing that the RFR-based PM_{25} prediction models are relatively reliable and effective. RMSE is another performance measuring metric that is frequently used in research publications. The results showed that no specific conclusion could be drawn as to what the best model is. This study provided a concise and comprehensive reference for researchers in the field of a random forestbased machine learning model for $PM_{2.5}$ prediction.

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Authors' contribution

Conceptualization: Sherin Babu. **Data curation:** Sherin Babu. **Formal analysis:** Sherin Babu, Binu Thomas. **Funding acquisition:** Sherin Babu. **Investigation:** Sherin Babu, Binu Thomas. **Methodology:** Sherin Babu. **Project administration:** Binu Thomas. **Resources:** Binu Thomas. **Software:** Sherin Babu. **Supervision:** Binu Thomas. **Validation:** Binu Thomas. **Visualization:** Sherin Babu. **Writing–original draft:** Sherin Babu. **Writing–review & editing:** Sherin Babu, Binu Thomas.

Competing interests

The authors declare that there is no conflict of interests.

Ethical issues

The authors confirm that all data acquired during the research are as stated in the paper, and no data from the study has been or will be published elsewhere.

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